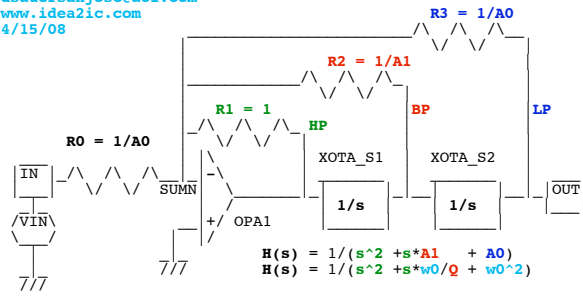


# State\_Variable\_OTA\_1KHz

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 \* www.idea2ic.com  
 \* 4/15/08



$$H(s) = 1/(s^2 + s*A1 + A0)$$

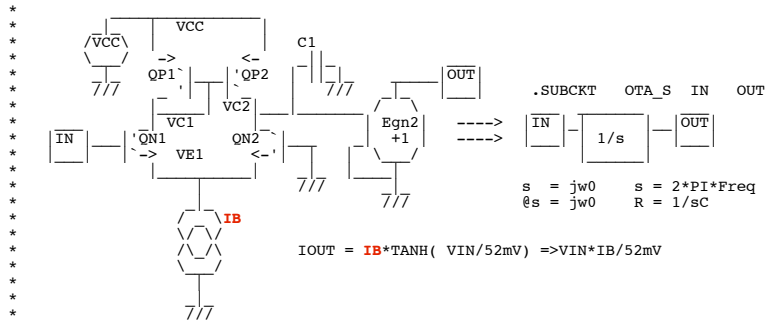
$$H(s) = 1/(s^2 + s*w0/Q + w0^2)$$

Set **A0 = 1** and scale **s** to 1KHz  
 Then **R2 = Q** and **s = 2\*PI\*1KHz**

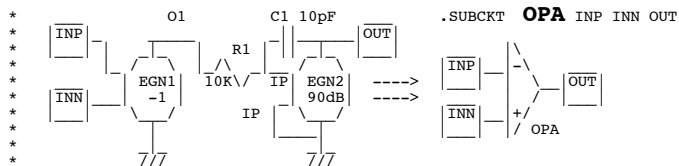
```
.OPTIONS GMIN=1e-12 METHOD=trap srcsteps = 1 gminsteps = 1
=====
V_IN VIN 0 AC 1 DC 0
R0 VIN SUMN 10k
R1 SUMN HP 10k
R2 SUMN BP 100k
R3 SUMN LP 10k
XOPA1 SUMN 0 HP OPA
XOTAS1 HP BP OTA_S
XOTAS2 BP LP OTA_S
.ac dec 50 10k
```

==OTAs Can Perform The Exact Same Function==

```
.control
run
plot db(bp) db(hp) db(lp) title StateVariable_Q_10
==Q Is Still Defined By FeedBack=====
alter R2 resistance = 10k
run
plot db(bp) db(hp) db(lp) title StateVariable_Q_1
.endc
```



[http://www.idea2ic.com/PlayWithJavascript/R\\_C\\_Freq.html](http://www.idea2ic.com/PlayWithJavascript/R_C_Freq.html)



```

.SUBCKT OPA INP INN OUT
EGN1 O1 0 INP INN -1
EGN2 OUT 0 IP 0 -1000000
R1 O1 IP 10k
C1 OUT IP 10p

```

.ends

```

.SUBCKT OTA_S IN OUT
QN1 VC1 IN VE1 NPNP
QN2 VC2 0 VE1 NPNP
QP1 VC1 VC1 VCC PNPP
QP2 VC2 VC1 VCC PNPP
IB VE1 0 5.2u
VCC VCC 0 DC 2
EGN2 OUT 0 VC2 0 +1
C1 VC2 0 .01592u

```

.ends

```

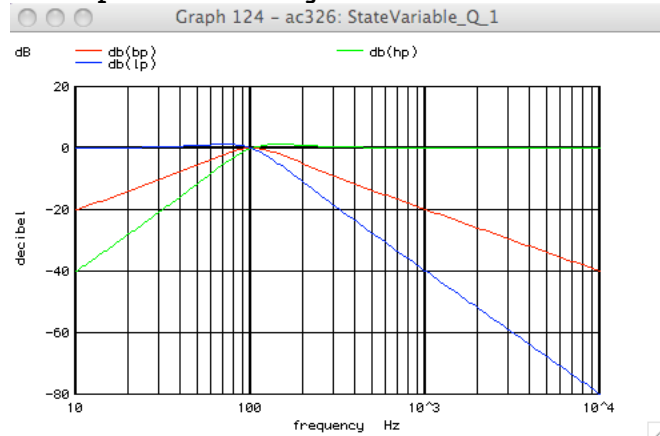
.model NPNP NPN( BF=2100 VAF=216 )
.model PNPP PNP( BF=2100 VAF=210 )

```

.end

=====END\_OF\_SPICE=====

A real OTA and capacitor with a voltage buffer can replace the integrator with no effect



Now R1->R3 independently controls Q  
The frequency however now is independently control by bias current IB of the OTA.

Graph 121 - ac323: StateVariable\_Q\_10

