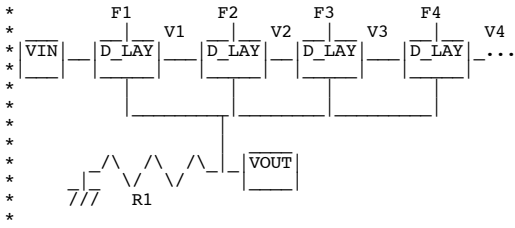


# =====FIR\_Hilbert\_SquareWave=====



The sanity check for the Hilbert response is a correct square wave response.

```

XZ_DLAY VIN VINZ CLK Z_DLAY
XS_DLAY1 VINZ V1 VOUT CLK F17N S_DLAY
XS_DLAY2 V1 V2 VOUT CLK F16N S_DLAY
XS_DLAY3 V2 V3 VOUT CLK F15N S_DLAY
XS_DLAY4 V3 V4 VOUT CLK F14N S_DLAY
XS_DLAY5 V4 V5 VOUT CLK F13N S_DLAY
XS_DLAY6 V5 V6 VOUT CLK F12N S_DLAY
XS_DLAY7 V6 V7 VOUT CLK F11N S_DLAY
XS_DLAY8 V7 V8 VOUT CLK F10N S_DLAY
XS_DLAY9 V8 V9 VOUT CLK F9N S_DLAY
XS_DLAY10 V9 V10 VOUT CLK F8N S_DLAY
XS_DLAY11 V10 V11 VOUT CLK F7N S_DLAY
XS_DLAY12 V11 V12 VOUT CLK F6N S_DLAY
XS_DLAY13 V12 V13 VOUT CLK F5N S_DLAY
XS_DLAY14 V13 V14 VOUT CLK F4N S_DLAY
XS_DLAY15 V14 V15 VOUT CLK F3N S_DLAY
XS_DLAY16 V15 V16 VOUT CLK F2N S_DLAY
XS_DLAY17 V16 V17 VOUT CLK F1 S_DLAY
XS_DLAY18 V17 V18 VOUT CLK F2 S_DLAY
XS_DLAY19 V18 V19 VOUT CLK F3 S_DLAY
XS_DLAY20 V19 V20 VOUT CLK F4 S_DLAY
XS_DLAY21 V20 V21 VOUT CLK F5 S_DLAY
XS_DLAY22 V21 V22 VOUT CLK F6 S_DLAY
XS_DLAY23 V22 V23 VOUT CLK F7 S_DLAY
XS_DLAY24 V23 V24 VOUT CLK F8 S_DLAY
XS_DLAY25 V24 V25 VOUT CLK F9 S_DLAY
XS_DLAY26 V25 V26 VOUT CLK F10 S_DLAY
XS_DLAY27 V26 V27 VOUT CLK F11 S_DLAY
XS_DLAY28 V27 V28 VOUT CLK F12 S_DLAY
XS_DLAY29 V28 V29 VOUT CLK F13 S_DLAY
XS_DLAY30 V29 V30 VOUT CLK F14 S_DLAY
XS_DLAY31 V30 V31 VOUT CLK F15 S_DLAY
XS_DLAY32 V31 V32 VOUT CLK F16 S_DLAY
XS_DLAY33 V32 V33 VOUT CLK F16 S_DLAY
VF1 F1 0 DC 0
VF2 F2 0 DC +0.318
VF3 F3 0 DC +0.000
VF4 F4 0 DC +0.106
VF5 F5 0 DC +0.000
VF6 F6 0 DC +0.064
VF7 F7 0 DC +0.000
VF8 F8 0 DC +0.045
VF9 F9 0 DC +0.000
VF10 F10 0 DC +0.035
VF11 F11 0 DC +0.000
VF12 F12 0 DC +0.029
VF13 F13 0 DC +0.000
VF14 F14 0 DC +0.025
VF15 F15 0 DC +0.000
VF16 F16 0 DC +0.020
VF17 F17 0 DC +0.000
VF1N F1N 0 DC 0
VF2N F2N 0 DC -0.318
VF3N F3N 0 DC -0.000
VF4N F4N 0 DC -0.106
VF5N F5N 0 DC -0.000
VF6N F6N 0 DC -0.064
VF7N F7N 0 DC -0.000
VF8N F8N 0 DC -0.045
VF9N F9N 0 DC -0.000
VF10N F10N 0 DC -0.035
VF11N F11N 0 DC -0.000
VF12N F12N 0 DC -0.029
VF13N F13N 0 DC -0.000
VF14N F14N 0 DC -0.025
VF15N F15N 0 DC -0.000
VF16N F16N 0 DC -0.020
VF17N F17N 0 DC -0.000
*TRAN TSTEP TSTOP TSTART TMAX ?UIC?
.tran 30u 1 0 30u UIC
.control
run
set pensize = 2
plot v17 vout
.endc

```



```

VF5      F5      0      DC      +0.000
VF6      F6      0      DC      +0.064
VF7      F7      0      DC      +0.000
VF8      F8      0      DC      +0.045
VF9      F9      0      DC      +0.000
VF10     F10     0      DC      +0.035
VF11     F11     0      DC      +0.000
VF12     F12     0      DC      +0.029
VF13     F13     0      DC      +0.000
VF14     F14     0      DC      +0.025
VF15     F15     0      DC      +0.000
VF16     F16     0      DC      +0.020
VF17     F17     0      DC      +0.000
VF1N     F1N     0      DC      0
VF2N     F2N     0      DC      -0.318
VF3N     F3N     0      DC      -0.000
VF4N     F4N     0      DC      -0.106
VF5N     F5N     0      DC      -0.000
VF6N     F6N     0      DC      -0.064
VF7N     F7N     0      DC      -0.000
VF8N     F8N     0      DC      -0.045
VF9N     F9N     0      DC      -0.000
VF10N    F10N    0      DC      -0.035
VF11N    F11N    0      DC      -0.000
VF12N    F12N    0      DC      -0.029
VF13N    F13N    0      DC      -0.000
VF14N    F14N    0      DC      -0.025
VF15N    F15N    0      DC      -0.000
VF16N    F16N    0      DC      -0.020
VF17N    F17N    0      DC      -0.000

```

```

XZ_DLAY  VIN      VINZ   CLK      Z_DLAY
XS_DLAY1 VINZ     V1      VOUT    CLK    F17N  S_DLAY
XS_DLAY2 V1       V2      VOUT    CLK    F16N  S_DLAY
XS_DLAY3 V2       V3      VOUT    CLK    F15N  S_DLAY
XS_DLAY4 V3       V4      VOUT    CLK    F14N  S_DLAY
XS_DLAY5 V4       V5      VOUT    CLK    F13N  S_DLAY
XS_DLAY6 V5       V6      VOUT    CLK    F12N  S_DLAY
XS_DLAY7 V6       V7      VOUT    CLK    F11N  S_DLAY
XS_DLAY8 V7       V8      VOUT    CLK    F10N  S_DLAY
XS_DLAY9 V8       V9      VOUT    CLK    F9N   S_DLAY
XS_DLAY10 V9      V10     VOUT    CLK    F8N   S_DLAY
XS_DLAY11 V10     V11     VOUT    CLK    F7N   S_DLAY
XS_DLAY12 V11     V12     VOUT    CLK    F6N   S_DLAY
XS_DLAY13 V12     V13     VOUT    CLK    F5N   S_DLAY
XS_DLAY14 V13     V14     VOUT    CLK    F4N   S_DLAY
XS_DLAY15 V14     V15     VOUT    CLK    F3N   S_DLAY
XS_DLAY16 V15     V16     VOUT    CLK    F2N   S_DLAY
XS_DLAY17 V16     V17     VOUT    CLK    F1    S_DLAY
XS_DLAY18 V17     V18     VOUT    CLK    F2    S_DLAY
XS_DLAY19 V18     V19     VOUT    CLK    F3    S_DLAY
XS_DLAY20 V19     V20     VOUT    CLK    F4    S_DLAY
XS_DLAY21 V20     V21     VOUT    CLK    F5    S_DLAY
XS_DLAY22 V21     V22     VOUT    CLK    F6    S_DLAY
XS_DLAY23 V22     V23     VOUT    CLK    F7    S_DLAY
XS_DLAY24 V23     V24     VOUT    CLK    F8    S_DLAY
XS_DLAY25 V24     V25     VOUT    CLK    F9    S_DLAY
XS_DLAY26 V25     V26     VOUT    CLK    F10   S_DLAY
XS_DLAY27 V26     V27     VOUT    CLK    F11   S_DLAY
XS_DLAY28 V27     V28     VOUT    CLK    F12   S_DLAY
XS_DLAY29 V28     V29     VOUT    CLK    F13   S_DLAY
XS_DLAY30 V29     V30     VOUT    CLK    F14   S_DLAY
XS_DLAY31 V30     V31     VOUT    CLK    F15   S_DLAY
XS_DLAY32 V31     V32     VOUT    CLK    F16   S_DLAY
XS_DLAY33 V32     V33     VOUT    CLK    F16   S_DLAY

```

```
R1      VOUT  0      3
```

```

*TRAN      TSTEP  TSTOP  TSTART  TMAX  ?UIC?
.tran      30u    2      0      30u    UIC

```

```

.control
run
set      pensize = 2
plot     v17 vout

```

```

.endc
*=====Switch_Model=====

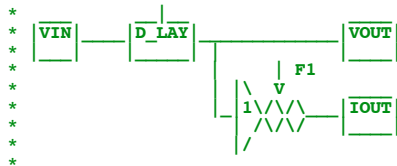
```

```
.MODEL SW SW( VT=.5 VH=.1 RON=100m ROFF=100MEG)
```

```

*=====SCALED_DELAY=====
*
* CLK

```



```

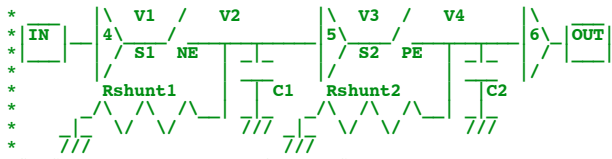
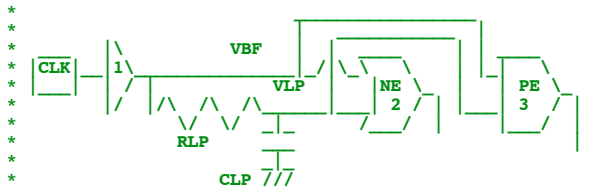
.SUBCKT S_DLAY VIN      VOUT  IOUT  CLK  F1
XZ_DLAY  VIN      VOUT  CLK  Z_DLAY
BOUT     IOUT     0      I      = -V(VOUT)*V(F1)
.ENDS    S_DLAY

```

```

*=====Z_DLAY=====

```



```

.SUBCKT Z_DELAY VIN OUT CLK
B1 VBF 0 V = u( v(CLK) -.5 )
R1 V1 0 V = V(VIN)
R2 V2 0 V = V(VIN)
R3 V3 0 V = V(VIN)
R4 V4 0 V = V(VIN)
R5 V5 0 V = V(VIN)
R6 V6 0 V = V(VIN)
R7 V7 0 V = V(VIN)
R8 V8 0 V = V(VIN)
R9 V9 0 V = V(VIN)
R10 V10 0 V = V(VIN)
R11 V11 0 V = V(VIN)
R12 V12 0 V = V(VIN)
R13 V13 0 V = V(VIN)
R14 V14 0 V = V(VIN)
R15 V15 0 V = V(VIN)
R16 V16 0 V = V(VIN)
R17 V17 0 V = V(VIN)
R18 V18 0 V = V(VIN)
R19 V19 0 V = V(VIN)
R20 V20 0 V = V(VIN)
R21 V21 0 V = V(VIN)
R22 V22 0 V = V(VIN)
R23 V23 0 V = V(VIN)
R24 V24 0 V = V(VIN)
R25 V25 0 V = V(VIN)
R26 V26 0 V = V(VIN)
R27 V27 0 V = V(VIN)
R28 V28 0 V = V(VIN)
R29 V29 0 V = V(VIN)
R30 V30 0 V = V(VIN)
R31 V31 0 V = V(VIN)
R32 V32 0 V = V(VIN)
R33 V33 0 V = V(VIN)
R34 V34 0 V = V(VIN)
R35 V35 0 V = V(VIN)
R36 V36 0 V = V(VIN)
R37 V37 0 V = V(VIN)
R38 V38 0 V = V(VIN)
R39 V39 0 V = V(VIN)
R40 V40 0 V = V(VIN)
R41 V41 0 V = V(VIN)
R42 V42 0 V = V(VIN)
R43 V43 0 V = V(VIN)
R44 V44 0 V = V(VIN)
R45 V45 0 V = V(VIN)
R46 V46 0 V = V(VIN)
R47 V47 0 V = V(VIN)
R48 V48 0 V = V(VIN)
R49 V49 0 V = V(VIN)
R50 V50 0 V = V(VIN)
C1 V1 0 1u
C2 V2 0 1u
C3 V3 0 1u
C4 V4 0 1u
C5 V5 0 1u
C6 V6 0 1u
C7 V7 0 1u
C8 V8 0 1u
C9 V9 0 1u
C10 V10 0 1u
C11 V11 0 1u
C12 V12 0 1u
C13 V13 0 1u
C14 V14 0 1u
C15 V15 0 1u
C16 V16 0 1u
C17 V17 0 1u
C18 V18 0 1u
C19 V19 0 1u
C20 V20 0 1u
C21 V21 0 1u
C22 V22 0 1u
C23 V23 0 1u
C24 V24 0 1u
C25 V25 0 1u
C26 V26 0 1u
C27 V27 0 1u
C28 V28 0 1u
C29 V29 0 1u
C30 V30 0 1u
C31 V31 0 1u
C32 V32 0 1u
C33 V33 0 1u
C34 V34 0 1u
C35 V35 0 1u
C36 V36 0 1u
C37 V37 0 1u
C38 V38 0 1u
C39 V39 0 1u
C40 V40 0 1u
C41 V41 0 1u
C42 V42 0 1u
C43 V43 0 1u
C44 V44 0 1u
C45 V45 0 1u
C46 V46 0 1u
C47 V47 0 1u
C48 V48 0 1u
C49 V49 0 1u
C50 V50 0 1u
B2 V1 0 V = 1-u( u(v(VBF) -.5)+u(.5 -v(VLP) ) -.1)
B3 V2 0 V = u( u(v(VBF) -.5)*u(.5 -v(VLP) ) -.1)
B4 V3 0 V = V(VIN)
B5 V4 0 V = V(V2)
B6 V5 0 V = V(V4)
.ENDS Z_DELAY

```

.end

6.7.11\_1.04PM  
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