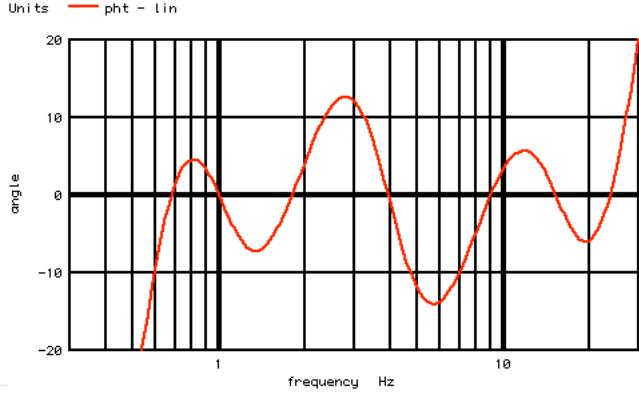
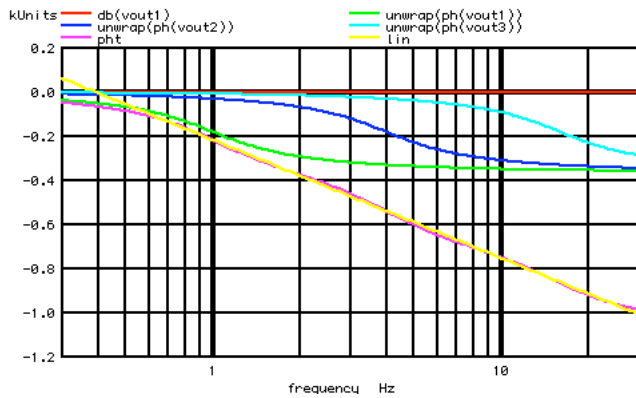


There will be some nonlinearity cancellation happening between the three all pass filters. The closer these filters are frequency spaced apart, the better the cancellation.

```
alter vfc2 dc = 4
```

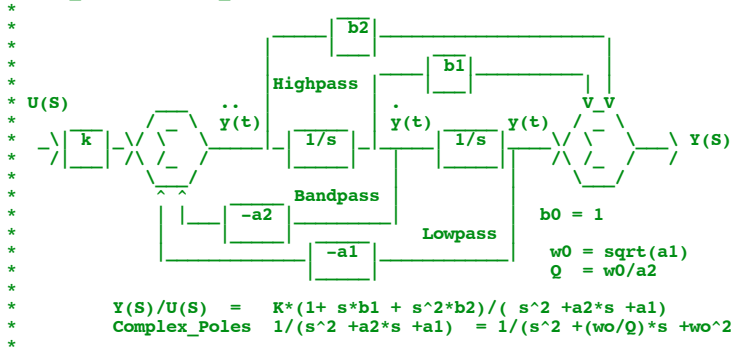
The DC control voltages make it easy to use an alter statement to adjust the frequency spacing.



Increasing the frequency spacing does degrade the nonlinearity cancellation, but it also extends the linearity over a greater frequency range.

=====**Full Netlist For Copy Paste**=====

Simple_StateVariable_Cell



$$Y(S)/U(S) = K*(1 + s*b1 + s^2*b2)/(s^2 + a2*s + a1)$$

$$\text{Complex Poles } 1/(s^2 + a2*s + a1) = 1/(s^2 + (w0/Q)*s + w0^2)$$

```
*.OPTIONS GMIN=1p METHOD=TRAP ABSTOL=1u TEMP=27 srcsteps = 1
*.OPTIONS RELTOL=.001 ABSTOL=1n VNTOL=1n ITL4=500
.OPTIONS GMIN=1p srcsteps = 1 ITL1=4000 gminsteps = 1
```

*=====Create Signal=====

VIN	VIN	0	DC	0	AC	1									
VFC1	FC1	0	DC	1											
VFC2	FC2	0	DC	3											
BVFC3	FC3	0	V	= V(FC2)*V(FC2)											
VK	K	0	DC	1											
VA1	A1	0	DC	1											
VA2	A2	0	DC	1											
VB0	B0	0	DC	1											
VB1	B1	0	DC	-1											
VB2	B2	0	DC	1											
XStateS1	VIN	FC1	K	A1	A2	B0	B1	B2	VOUT1	HP	BP	LP	StateVS		
XStateS2	VIN	FC2	K	A1	A2	B0	B1	B2	VOUT2	HP2	BP2	LP2	StateVS		
XStateS3	VIN	FC3	K	A1	A2	B0	B1	B2	VOUT3	HP3	BP3	LP3	StateVS		

```

.control
set pensize = 2
*AC DECLin NUMDEC FSTART FSTOP
ac dec 100 .3 30
let pht = unwrap(ph(vout1)) + unwrap(ph(vout2)) + unwrap(ph(vout3))

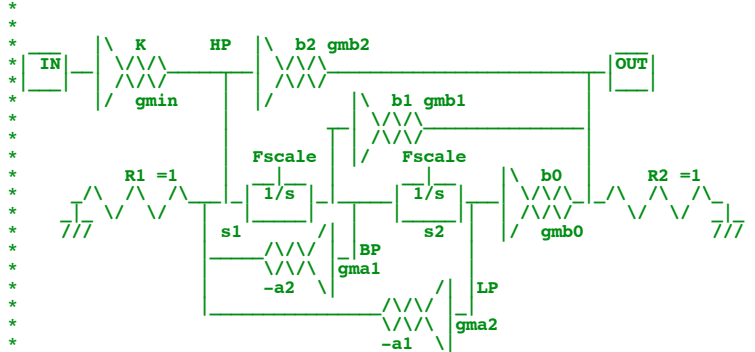
let lin = -640*log(frequency) -235
plot db(vout1) ylimit -1 1 title gain_Flatness
plot db(vout1) unwrap(ph(vout1)) title AllPass
plot db(vout1) unwrap(ph(vout1)) unwrap(ph(vout2)) unwrap(ph(vout3)) pht lin title AllPassOut
plot pht - lin title Fshift_3 ylimit -20 20

alter vfc2 dc = 4
ac dec 100 .3 30
let pht = unwrap(ph(vout1)) + unwrap(ph(vout2)) + unwrap(ph(vout3))

let lin = -535*log(frequency) -217
plot db(vout1) unwrap(ph(vout1)) unwrap(ph(vout2)) unwrap(ph(vout3)) pht lin title AllPassOut
plot pht - lin title Fshift_4 ylimit -20 20
.endc

```

*=====StateVariable_Cell_S=====

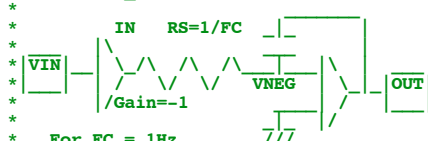


```

.SUBCKT StateVS VIN FC K A1 A2 B0 B1 B2 VOUT HP BP LP
R1 HP 0 1
R2 OUT 0 1
Bgmin HP 0 I = -V(VIN)*V(K)*1
Bgma1 HP 0 I = V(LP)*V(A1)
Bgma2 HP 0 I = (V(BP))*V(A2)
Bgmb0 OUT 0 I = -V(LP)*V(B0)
Bgmb1 OUT 0 I = -V(BP)*V(B1)
Bgmb2 OUT 0 I = -V(HP)*V(B2)
XS1block HP BP FC Sblock
XS2block BP LP FC Sblock
BOUT VOUT 0 V = V(OUT)
.ENDS StateVS

```

*=====S_BLOCK=====



```

* For FC = 1Hz
* RS = 1 Ohm CS=1uF/2Pi
* Xc = 1 Ohm
.SUBCKT Sblock VIN OUT FC
Bbuf IN 0 V = -V(VIN)
BRS IN VNEG I = (V(IN)-V(VNEG))*V(FC)
Cs VNEG OUT .159
BSOUT OUT 0 V = -V(VNEG)*3000
.ENDS Sblock

```

.end

6.7.11_12.30PM
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Don Sauer