A simple Asynchronous ADC

(Auto-Folding Multi-Bit Comparator) (US Pat. 7839317)



A Simple 4Bit 1GHz Level-Crossing A to D

This invention could have been invented in the late 60's. Would a high speed comparator which provides a multi-bit output been useful back then? And the architecture is simple and all NPN. The circuit shown above is actually the full schematic for a 4 bit 1GHz asynchronous level crossing A to D. The digital elements shown in blue are not drawn at transistor level since differential logic needs to be used. All the DC reference currents shown in green match each other in current value. All NPNs are minimum 1X geometries, and the reference currents are chosen to run all NPNs at their maximum ftau. The analog input shown in red is an input current having a full scale range from zero to the reference current level. When the NPNs are modeled as having a ftau at 4GHz, the digital output response to a full scale 16ns ramp input current is shown below.



Each cell is doing a current comparison to the reference current, but it is also outputting a folded version of the analog signal current as well. Some simple first order speed up techniques have been applied to allow 4GHz NPNs to track a moving input with no missing codes at a 1GHz rate. Some much better modeling, and some more advanced speed up techniques might allow the LSB tracking output code rate to come even closer to the ftau of the transistors.

The XOR logic circuit is reformatting the digital output into the normal binary format. Notice how when the MSB reverses state, all the other bits need to reverse state at the same time.



The pre-processed digital output has an interesting format. Only one cell is able to switch state at a given time. When any of the cells switch state, all the other cells are stationary. So a single output state change could trigger all the bits to be cleanly sampled. The XOR function can then be applied later at any time.



The comparator cell was actually invented as a way to perform an absolute value function on two input current sources (4,069,460). It has since then found other uses, such as for a precise AM decoder for use in an AM stereo decoder (4,359,693).

The circuit is essentially a dual input current mirror in which the larger of two input currents take over the current mirror. Some voltage clamping transistors prevent saturation while provide an output current equal to the absolute difference between the two input currents. If Iin is 0.2mA larger than Iref, 1.2mA will flow in Qn1 and Qn2. Transistors Qn4 and Qn6 will be off. And transistor Qn5 will make up the 0.2mA difference in input current.



Now if the Iin current is ramping up, it becomes obvious that the input current is both being compared and folded at the output at the same time. The comparator's differential input voltage will toggle around the reference current, and can be used as a differential digital output port. The absolute value output current happens to be the input current folded around the reference current. This folded output current can be sent to another stage, and the analog signal gets compared and folded a again.



The current processing of the signal is mathematical. Each stage compares the current between an analog input current and a reference current. The analog input current further gets folded to an absolute value of the difference between the two input currents. This folded output current can then be passed on to a series of following stages.



But the folding of the analog signal is being done just like it would be done on a piece of paper. Every fold means a half reduction in magnitude. This means that the reference currents will have to be reduced by a factor of two at each stage. A need for speed makes it desirable to use minimum geometries for all transistors in the signal path. And all the transistors need to operate at an optimum current level to have a maximum ftau.



High Speed Simulation Bit Block

Some simple first order techniques to address speed issues are shown in the circuit above. Transistors Qn6 and Qn5 make up for the gain reduction happening at each current fold. A NPN transistor which has a 4GHz ftau is being used as a model. This NPN has an optimum ftau around 1mA. Transistors Qn1 to Qn4 all want to be biased up to run as fast as possible. Diode D6 and resistor R6b are biasing Qn3 and Qn4. Degeneration resistors at Qn1 and Qn2 may be desirable to enhance matching.

The biggest problem is when a transistor turns off, it often takes a while to turn back on. So transistors Qn7 and Qn8 have pick up the additional job of being clamping diodes. The voltages between the bases of Qn3 and Qn4 is the actual digital output. These nodes are going to want to go to some differential logic stage. Raising the Vbias voltage applied to Qn7 and Qn8 will begin to limit the voltage swing of the differential digital output. So Vbias can control the degree to which transistors like Qn3, Qn4, Qn7 and Qn8 can turn off. So how little of a input voltage does internal differential logic need? A swing around +/- 50mV between the bases of Qn3 and Qn4 might be a good place to start.



Output current for a 160ns Input Ramp

Whenever something turns off, it will have a little delay at turning back on. In amplifier applications, this is often called cross over distortion. It will create a glitch for a short amount of time. Biasing transistors to stay on will reduce this effect.



Using the higher speed cells, the connection of the cells has becomes easier. Everything gets biased to the same reference current of 1mA. This tends to biases all NPNs at a maximum ftau.



a 160ns Ramp

The crossover glitches have a convenient format. They appear to want to distort all the folded analog waveforms at their endpoints. This is convenient in that the critical current comparison is always happening at the center of the folded waveforms.



But folding every stage means that currents get toggled twice as fast for every bit stage. When toggling speeds approach the ftau of the transistors, the crossover glitches may no longer be at just the endpoints. At high enough speeds, they begin to migrate away from the endpoints, and start interfering with the current comparison process.

This is an interesting type of failure. It means that missing lsb codes starts to appear at higher input slew rates. So there is a bit resolution versus input slew rate tradeoff. Put in a faster moving analog signal, and get a lower bit resolution digital output.



Simulation suggests that 4 cells can track a 16nsec full scale ramp and produce all 16 individual LSB codes at a rate of 1GHz per LSB. The ftau for the NPNs is only 4GHz. Only some simple speed up techniques were used to do this. Just how close the conversion rate can come to matching ftau is going to require an exception ability to match silicon to spice models.



Apply a Full scale 10Mhz sine wave to the input, and then mathematically reconstruct the digital output back into a analog waveform. This shows that the output transitions are not happening at a periodic rate. In some applications, this has the benefit in that the digital output is only changing state when something is actually happening.

This kind of digitizing of analog signal has been referred to as level crossing sampling, or as a threshold crossing detector, or as an Asynchronous Analog-to-Digital Converters, or even as a Level-Crossing Flash Asynchronous Analog-to-Digital Converter.

Where as a normal A to D stores it resolution in terms of a precise voltage level, this type of converter stores its resolution in terms of a precise time when something has happened. There has been some interest in using this type of a converter lately. The following are some recent examples of Asynchronous ADC activity off the web.

6 bit Asynchronous December 2006 Asynchronous ADC In CAD Mentor Graphics Asynchronous Data Processing System ASYNCHRONOUS PARALLEL RESISTORLESS ADC Flash Asynchronous Analog-to-Digital Converter Novel Asynchronous ADC Architecture LEVEL BASED SAMPLING FOR ENERGY CONSERVATION IN LARGE NETWORKS A Level-Crossing Flash Asynchronous Analog-to-Digital Converter Weight functions for signal reconstruction based on level crossings Adaptive Rate Filtering Technique Based on the Level Crossing Sampling Adaptive Level-Crossing Sampling Based DSP Systems A 0.8 V Asynchronous ADC for Energy Constrained Sensing Applications Spline-based signal reconstruction algorithm from multiple level crossing samples A New Class of Asynchronous Analog-to-Digital Converters Effects of time quantization and noise in level crossing sampling stabilization

Here is some more background information on Analog to Digital converters.

A 1-GS/s 6-bit 6.7-mW ADC A Study of Folding and Interpolating ADC Folding_ADCs_Tutorials high speed ADC design Investigation of a Parallel Resistorless ADC Here are some patents on the subject.

4,291,299 Analog_to_digital_converter_using_timed 4,352,999 Zero_crossing_comparators_with_threshold 4,544,914 Asynchronously_controllable_successive_approximation 4,558,348 Digital_video_signal_processing_system_using 5,001,364 Threshold_crossing_detector 5,315,284 Asynchronous_digital_threshold_detector_ 5,945,934 Tracking_analog_to_digital_converter 6,020,840 Method_and_apparatus_for_representing_waveform 6,492,929 Analogue_to_digital_converter_and_method 6,501,412 Analog_to_digital_converter_including_a_quantizers 6,667,707 Analog_to_digital_converter_with_asynchronous_ability 6,720,901 Interpolation_circuit_having_a_conversio2 6,850,180 SelfTimed_ADC 6,965,338 Cascade_A_D_converter 7,133,791 Two_mean_level_crossing_time_interval

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